# Fundamental Computer Science Sequence 1: Turing Machines

Denis Trystram (inspired by Giorgio Lucarelli)

MoSIG1, 2020

#### Classes

 30 hours in total (half Theory, half Exercises/Practice).

- ► 5 topics
  - 1. Universal Computing Model: the Turing Machine
  - 2. Alternative model:  $\lambda$ -Calculus
  - 3. NP-completeness
  - 4. Approximation Theory
  - 5. Introduction to Quantum Computing

#### Evaluation

- ► Exam: 70%
- ► Reading session: 30%

#### Books

- ► M. Garey and D. Johnson, Computers and Intractability: A Guide to the Theory of NP-Completeness, Freeman
- Harry Lewis and Christos Papadimitriou, *Elements of the Theory of Computation*, Prentice-Hall
- ► Christos Papadimitriou, Computational Complexity, Pearson
- S. Arora and B. Barak, Computational complexity a modern approach, Cambridge
- Vijay Vazirani, Approximation Algorithms, Springer
- ► Arnold Rosenberg, The pillars of Computation Theory, Springer

#### Objective of the session

 $\label{eq:present} Present \ (and \ discuss) \ the \ universal \ computational \ model \ of \ Turing \ machine.$ 

# Preliminary

What is an *Algorithm*?

# Preliminary

#### What is an *Algorithm*?

The first question is to discuss what can be calculated by a Computer.

**Informally**: this is a step-by-step procedure composed that solves a *problem*.

# Preliminary

#### What is an Algorithm?

The first question is to discuss what can be calculated by a Computer.

**Informally**: this is a step-by-step procedure composed that solves a *problem*.

Desired properties

- clearly defined steps (formalization)
- efficiency (complexity how many steps?)
- termination

# Short History

#### • Etymology:

- Al-Khwārizmī a Persian mathematician of the 9th century
- $\alpha \rho \iota \theta \mu \delta \varsigma$  the Greek word that means "number"
- Euclid's algorithm for computing the greatest common divisor (3rd century BC)
- ► End of 19th century beginning of 20th century: mathematical formalizations (proof systems, axioms, etc). Is there an algorithm for any problem?
- Entscheidungsproblem (a challenge proposed by David Hilbert 1928): create an algorithm which is able to decide if a mathematical statement is true in a finite number of operations
- Church-Turing thesis (1930's): provides a formal definition of an algorithm (λ-calculus, Turing machine) and show that a solution to Entscheidungsproblem does not exist

alphabet: a finite set of symbols

• examples: Roman alphabet  $\{a, b, \dots, z\}$ , binary alphabet  $\{0, 1\}$ 

alphabet: a finite set of symbols

• examples: Roman alphabet  $\{a, b, \dots, z\}$ , binary alphabet  $\{0, 1\}$ 

string: a finite sequence of symbols over an alphabet

- ► examples: *science*, 0011101
- $\blacktriangleright$   $\epsilon$ : the empty string
- $\Sigma^*$ : the set of all strings over an alphabet  $\Sigma$  (including  $\epsilon$ )

alphabet: a finite set of symbols

• examples: Roman alphabet  $\{a, b, \ldots, z\}$ , binary alphabet  $\{0, 1\}$ 

string: a finite sequence of symbols over an alphabet

- ► examples: *science*, 0011101
- $\blacktriangleright$   $\epsilon$ : the empty string
- $\Sigma^*$ : the set of all strings over an alphabet  $\Sigma$  (including  $\epsilon$ )

language: a set strings over an alphabet  $\Sigma$  (i.e., a subset of  $\Sigma^*$ )

- examples:  $\emptyset$ ,  $\Sigma$ ,  $\Sigma^*$
- more examples:

$$\begin{split} L &= \{w \in \Sigma^* : w \text{ has some property } P\} \\ L &= \{w \in \Sigma^* : w = w^R\} \quad (w^R = \text{reverse of } w) \\ L &= \{w \in \{0, 1\}^* : w \text{ has an equal number of 0's and 1's} \end{split}$$

alphabet: a finite set of symbols

• examples: Roman alphabet  $\{a, b, \dots, z\}$ , binary alphabet  $\{0, 1\}$ 

string: a finite sequence of symbols over an alphabet

- ► examples: *science*, 0011101
- $\blacktriangleright$   $\epsilon$ : the empty string
- $\Sigma^*$ : the set of all strings over an alphabet  $\Sigma$  (including  $\epsilon$ )

language: a set strings over an alphabet  $\Sigma$  (i.e., a subset of  $\Sigma^*$ )

- examples:  $\emptyset$ ,  $\Sigma$ ,  $\Sigma^*$
- more examples:

$$\begin{split} &L = \{w \in \Sigma^* : w \text{ has some property } P\} \\ &L = \{w \in \Sigma^* : w = w^R\} \quad (w^R = \text{reverse of } w) \\ &L = \{w \in \{0, 1\}^* : w \text{ has an equal number of 0's and 1's}\} \\ &L = \{w \in \{1, 2, \dots, n\} : w \text{ is a permutation of } \{1, 2, \dots, n\} \\ & \text{ corresponding to a Hamiltonian Path}\} \end{split}$$

Define first what is a *problem*. An id, the list of input (with their coding) and a question.

Define first what is a *problem*.

An id, the list of input (with their coding) and a question.

Decision problem: a problem that can be posed as an yes/no question.

Define first what is a *problem*.

An id, the list of input (with their coding) and a question.

Decision problem: a problem that can be posed as an yes/no question.

example:
 Prime
 Given a integer n
 ls n a prime?

Define first what is a *problem*.

An id, the list of input (with their coding) and a question.

Decision problem: a problem that can be posed as an yes/no question.

- example:
  Prime
  Given a integer n
  Is n a prime?
- ► another example:
  - ► Given a graph G = (V, E), is there a permutation  $\pi$  of the vertex set such that  $(v_{\pi(i)}, v_{\pi(i+1)}) \in E$  for all  $i, 1 \le i \le |V-1|$ ?

Define first what is a *problem*.

An id, the list of input (with their coding) and a question.

Decision problem: a problem that can be posed as an yes/no question.

- example:
  Prime
  Given a integer n
  Is n a prime?
- ► another example:
  - ▶ Given a graph G = (V, E), is there a permutation  $\pi$  of the vertex set such that  $(v_{\pi(i)}, v_{\pi(i+1)}) \in E$  for all  $i, 1 \leq i \leq |V 1|$ ? (Hamiltonian Path)

# Beyond decision problems

Optimization: a problem of searching for the best answer

## Beyond decision problems

Optimization: a problem of searching for the best answer

▶ example: Given a graph G = (V, E), two vertices  $s, t \in V$  and an integer distance d(e) for each  $e \in E$ , find the path p between s and t such that the sum of distances of the edges in p is minimized.

Optimization: a problem of searching for the best answer

- ▶ example: Given a graph G = (V, E), two vertices  $s, t \in V$  and an integer distance d(e) for each  $e \in E$ , find the path p between s and t such that the sum of distances of the edges in p is minimized.
- ▶ decision version: Given a graph G = (V, E), two vertices  $s, t \in V$ , an integer distance d(e) for each  $e \in E$  and an integer D, is there a path p between s and t such that the sum of distances of the edges in p is at most D?

Observation 1:

In most of these lectures we will deal with decision problems

#### Observation 1:

In most of these lectures we will deal with decision problems

#### Observation 2:

A decision problem is defined by the input and the yes/no question

- examples of input:
  - Given a set of numbers  $A = \{a_1, a_2, \dots, a_n\}$
  - Given a graph G = (V, E)
  - ▶ Given a graph G = (V, E) and a positive weight w(e) for each  $e \in E$

#### Observation 1:

In most of these lectures we will deal with decision problems

#### Observation 2:

A decision problem is defined by the input and the yes/no question

- examples of input:
  - Given a set of numbers  $A = \{a_1, a_2, \dots, a_n\}$
  - Given a graph G = (V, E)
  - $\blacktriangleright$  Given a graph G=(V,E) and a positive weight w(e) for each  $e\in E$
- $\blacktriangleright$  < I >: string encoding of the input
  - $\blacktriangleright$  <  $a_1, a_2, \ldots, a_n$  >
  - < adjacency matrix of G >
  - < adjacency matrix of  $G, w(e) \ \forall e \in E >$

#### Observation 1:

In most of these lectures we will deal with decision problems

#### Observation 2:

A decision problem is defined by the input and the yes/no question

- examples of input:
  - Given a set of numbers  $A = \{a_1, a_2, \dots, a_n\}$
  - Given a graph G = (V, E)
  - $\blacktriangleright$  Given a graph G=(V,E) and a positive weight w(e) for each  $e\in E$
- $\blacktriangleright$  < I >: string encoding of the input
  - $\blacktriangleright$  <  $a_1, a_2, \ldots, a_n$  >
  - < adjacency matrix of G >
  - < adjacency matrix of  $G, w(e) \ \forall e \in E >$
- |I|: size of the input (in binary)
  - $\blacktriangleright \log_2 a_1 + \log_2 a_2 + \ldots \log_2 a_n$
  - $|V|^2$
  - $\bullet |V|^2 + \sum_{e \in E} \log_2 w(e)$

# Turing machine

#### memory: an infinite tape

- initially, it contains the input string
- move the head left or right
- read and/or write to current cell
- control states
  - finite number of them
  - one current state
- At each step:
  - move from state to state
  - read or write or move Left or move Right in the tape



# Turing machine: formal definition

A Turing Machine (M) is a six-tuple  $(K, \Sigma, \Gamma, \delta, s, H)$ , where

- K is a finite set of states
- $\blacktriangleright\ \Sigma$  is the input alphabet not containing the  $\mathit{blank}$  symbol  $\sqcup$
- $\blacktriangleright\ \Gamma$  is the tape alphabet, where  $\sqcup\in\Gamma$  and  $\Sigma\subseteq\Gamma$
- $s \in K$ : the initial state
- $H \subseteq K$ : the set of halting states
- ►  $\delta$ : the transition function from  $(K \setminus H) \times \Gamma$  to  $K \times (\Gamma \cup \{\leftarrow, \rightarrow\})$

# Turing machine: formal definition

A Turing Machine (M) is a six-tuple  $(K, \Sigma, \Gamma, \delta, s, H)$ , where

- K is a finite set of states
- $\blacktriangleright\ \Sigma$  is the input alphabet not containing the  $\mathit{blank}$  symbol  $\sqcup$
- $\blacktriangleright\ \Gamma$  is the tape alphabet, where  $\sqcup\in\Gamma$  and  $\Sigma\subseteq\Gamma$
- $s \in K$ : the initial state
- $H \subseteq K$ : the set of halting states
- $\delta$ : the transition function from  $(K \setminus H) \times \Gamma$  to  $K \times (\Gamma \cup \{\leftarrow, \rightarrow\})$

In general,  $\delta(q,a)=(p,b)$  means that when M is in the state q and reads a in the tape, it goes to the state p and

- if  $b \in \Sigma$ , writes b in the place of a
- if  $b \in \{\leftarrow, \rightarrow\}$ , moves the head either Left or Right



q	$\sigma$	$\delta(q,\sigma)$
$q_0$	a	$(q_1,\sqcup)$
$q_0$	$\Box$	$(h,\sqcup)$
$q_1$	a	$(q_0, a)$
$q_1$	$\Box$	$(q_0, \rightarrow)$



q	$\sigma$	$\delta(q,\sigma)$
$q_0$	a	$(q_1,\sqcup)$
$q_0$	$\Box$	$(h,\sqcup)$
$q_1$	a	$(q_0, a)$
$q_1$	$\Box$	$(q_0, \rightarrow)$



 $(q_0, \underline{a}aa)$ 

Consider the Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, H)$  where  $K = \{q_0, q_1, h\}, \quad \Sigma = \{a\}, \quad \Gamma = \{a, \sqcup\}, \quad s = q_0, \quad H = \{h\},$ and  $\delta$  is given by the table. How does M proceed?

q	$\sigma$	$\delta(q,\sigma)$
$q_0$	a	$(q_1,\sqcup)$
$q_0$	$\Box$	$(h,\sqcup)$
$q_1$	a	$(q_0, a)$
$q_1$	$\Box$	$(q_0, \rightarrow)$



 $(q_0,\underline{a}aa) \vdash_M (q_1,\underline{\sqcup}aa)$ 

Consider the Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, H)$  where  $K = \{q_0, q_1, h\}, \quad \Sigma = \{a\}, \quad \Gamma = \{a, \sqcup\}, \quad s = q_0, \quad H = \{h\},$ and  $\delta$  is given by the table. How does M proceed?



 $(q_0,\underline{a}aa) \vdash_M (q_1,\underline{\sqcup}aa) \vdash_M (q_0,\underline{\sqcup}\underline{a}a)$ 



$$\begin{array}{rcl} (q_0,\underline{a}aa) & \vdash_M & (q_1,\underline{\sqcup}aa) & \vdash_M & (q_0,\underline{\sqcup}\underline{a}a) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}a) \end{array}$$



$$\begin{array}{ccc} (q_0,\underline{a}aa) & \vdash_M & (q_1,\underline{\sqcup}aa) & \vdash_M & (q_0,\underline{\sqcup}\underline{a}a) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}a) & \vdash_M & (q_0,\underline{\sqcup} \perp \underline{a}) \end{array}$$



$$\begin{array}{cccc} (q_0,\underline{a}aa) & \vdash_M & (q_1,\underline{\sqcup}aa) \vdash_M & (q_0,\underline{\sqcup}\underline{a}a) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}a) \vdash_M & (q_0,\underline{\sqcup}\underline{\sqcup}\underline{a}) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}) \end{array}$$



$$\begin{array}{cccc} (q_0,\underline{a}aa) & \vdash_M & (q_1,\underline{\sqcup}aa) \vdash_M & (q_0,\underline{\sqcup}\underline{a}a) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}a) \vdash_M & (q_0,\underline{\sqcup}\underline{\sqcup}\underline{a}) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}) \vdash_M & (q_0,\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}) \end{array}$$



$$\begin{array}{rcl} (q_0,\underline{a}aa) & \vdash_M & (q_1,\underline{\sqcup}aa) \vdash_M & (q_0,\underline{\sqcup}\underline{a}a) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}a) \vdash_M & (q_0,\underline{\sqcup}\underline{\sqcup}\underline{a}) \\ & \vdash_M & (q_1,\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}) \vdash_M & (q_0,\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}) \\ & \vdash_M & (h,\underline{\sqcup}\underline{\sqcup}\underline{\sqcup}) \end{array}$$
### Definition

A configuration of a Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, H)$  is a member of  $K \times \Gamma^* \times \Gamma^*((\Gamma \setminus \{\sqcup\}) \cup \{\epsilon\})$ .

- ▶ informally: a triplet describing
  - the current state
  - the contents of the tape on the left of the head (including head's position)
  - the contents of the tape on the right of the head

### Definition

A configuration of a Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, H)$  is a member of  $K \times \Gamma^* \times \Gamma^*((\Gamma \setminus \{\sqcup\}) \cup \{\epsilon\})$ .

- ▶ informally: a triplet describing
  - the current state
  - the contents of the tape on the left of the head (including head's position)
  - the contents of the tape on the right of the head

• example:  $(q_1, \sqcup a, a)$  or simply  $(q_1, \sqcup \underline{a}a)$  or simply  $(q_1, \underline{a}a)$ 

### Definition

A configuration of a Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, H)$  is a member of  $K \times \Gamma^* \times \Gamma^*((\Gamma \setminus \{\sqcup\}) \cup \{\epsilon\})$ .

- ▶ informally: a triplet describing
  - the current state
  - the contents of the tape on the left of the head (including head's position)
  - the contents of the tape on the right of the head
- example:  $(q_1, \sqcup a, a)$  or simply  $(q_1, \sqcup \underline{a}a)$  or simply  $(q_1, \underline{a}a)$

Initial configuration:  $(s,\underline{a}w)$  where  $M = (K, \Sigma, \Gamma, \delta, s, H)$  is a Turing Machine,  $a \in \Sigma$ ,  $w \in \Sigma^*$  and aw is the *input string* 

### Definition

A configuration of a Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, H)$  is a member of  $K \times \Gamma^* \times \Gamma^*((\Gamma \setminus \{\sqcup\}) \cup \{\epsilon\})$ .

- ▶ informally: a triplet describing
  - the current state
  - the contents of the tape on the left of the head (including head's position)
  - the contents of the tape on the right of the head
- example:  $(q_1, \sqcup a, a)$  or simply  $(q_1, \sqcup \underline{a}a)$  or simply  $(q_1, \underline{a}a)$

Initial configuration:  $(s,\underline{a}w)$  where  $M = (K, \Sigma, \Gamma, \delta, s, H)$  is a Turing Machine,  $a \in \Sigma$ ,  $w \in \Sigma^*$  and aw is the *input string* 

Halted configuration: a configuration whose state belongs to H

 $\blacktriangleright \text{ example: } (h, \sqcup \sqcup \sqcup \sqcup, \epsilon) \text{ or simply } (h, \sqcup \sqcup \sqcup \sqcup) \text{ or simply } (h, \underline{\sqcup})$ 

### Definition

Consider a Turing Machine M and two configurations  $C_1$  and  $C_2$  of M. If M can go from  $C_1$  to  $C_2$  in a *single step*, then we write

 $C_1 \vdash_M C_2$ 

#### Definition

Consider a Turing Machine M and two configurations  $C_1$  and  $C_2$  of M. If M can go from  $C_1$  to  $C_2$  in a *single step*, then we write

 $C_1 \vdash_M C_2$ 

#### Definition

Consider a Turing Machine M and two configurations  $C_1$  and  $C_2$  of M. If M can go from  $C_1$  to  $C_2$  using a *sequence* of configurations, then we say that  $C_1$  yields  $C_2$  and we write

 $C_1 \vdash^*_M C_2$ 

#### Definition

Consider a Turing Machine M and two configurations  $C_1$  and  $C_2$  of M. If M can go from  $C_1$  to  $C_2$  in a *single step*, then we write

 $C_1 \vdash_M C_2$ 

#### Definition

Consider a Turing Machine M and two configurations  $C_1$  and  $C_2$  of M. If M can go from  $C_1$  to  $C_2$  using a *sequence* of configurations, then we say that  $C_1$  yields  $C_2$  and we write

 $C_1 \vdash^*_M C_2$ 

#### Definition

A computation of a Turing Machine M is a sequence of configurations  $C_0, C_1, \ldots, C_n$ , for some  $n \ge 0$ , such that

$$C_0 \vdash_M C_1 \vdash_M C_2 \vdash_M \ldots \vdash_M C_n$$

The **length** of the computation is n (or it performs n steps).

# Determinism or not?

### Definition

Implicitly, the transition  $\delta$  is deterministic.

### Determinism or not?

#### Definition

Implicitly, the transition  $\delta$  is deterministic.

Non-deterministic Turing Machine

What happens is several outputs are allowed at each step?

The choice is among k fixed possibilities, random, round-robin, etc.

### Determinism or not?

#### Definition

Implicitly, the transition  $\delta$  is deterministic.

#### Non-deterministic Turing Machine

What happens is several outputs are allowed at each step?

The choice is among k fixed possibilities, random, round-robin, etc.

This point will be detailed in the next lecture.

### A more general notation for Turing Machines



Turing Machine  $L_a = (K, \Sigma, \Gamma, \delta, s, H)$  where:  $-K = \{q_0, q_1\}$   $-a \in \Sigma$   $-s = q_0$  $-H = \{q_1\}$ 

### A more general notation for Turing Machines



Turing Machine  $L_a = (K, \Sigma, \Gamma, \delta, s, H)$  where:  $-K = \{q_0, q_1\}$   $-a \in \Sigma$   $-s = q_0$  $-H = \{q_1\}$ 

Define similar simple Turing Machines

• examples: L, R,  $L_a$ ,  $R_a$ ,  $L^2$ ,  $R^2$ , a,  $\sqcup$ , etc

### A more general notation for Turing Machines



Turing Machine  $L_a = (K, \Sigma, \Gamma, \delta, s, H)$  where:  $-K = \{q_0, q_1\}$   $-a \in \Sigma$   $-s = q_0$  $-H = \{q_1\}$ 

Define similar simple Turing Machines

• examples: L, R,  $L_a$ ,  $R_a$ ,  $L^2$ ,  $R^2$ , a,  $\sqcup$ , etc

► Combine simple machines to construct more complicated ones

1. Run  $M_1$ 

 $\begin{array}{c}
M_3 \\
\uparrow b \\
M_1 \xrightarrow{a} M_2
\end{array}$ 

- 2. If  $M_1$  finishes and the head reads a then run  $M_2$  starting from this a
- 3. Else run  $M_3$  starting from this b

What is the goal of the following Turing Machine?

$$\begin{array}{c} & & & \\ & & & \\ \searrow L_{\sqcup} \rightarrow R \xrightarrow{a \neq \sqcup} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a \\ & & & \\ & & \downarrow \sqcup \\ & & \\ & & \\ R_{\sqcup} \end{array}$$

What is the goal of the following Turing Machine?

$$> L_{\sqcup} \longrightarrow \underset{R_{\sqcup}}{\overset{a \neq \sqcup}{\longrightarrow}} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a$$

 $(\sqcup abc \underline{\sqcup}) \vdash^*_M (\underline{\sqcup} abc \sqcup) \qquad (L_{\sqcup})$ 

What is the goal of the following Turing Machine?

$$\begin{array}{c} & \swarrow \\ & \downarrow \\ > L_{\sqcup} \rightarrow R \xrightarrow{a \neq \sqcup} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a \\ & \downarrow \\ & \downarrow \\ & R_{\sqcup} \end{array}$$

What is the goal of the following Turing Machine?

$$\begin{array}{c} & \swarrow \\ & \downarrow \\ > L_{\sqcup} \rightarrow R \xrightarrow{a \neq \sqcup} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a \\ & \downarrow \\ & \downarrow \\ & R_{\sqcup} \end{array}$$

 $\begin{array}{cccc} (\sqcup abc \sqcup) & \vdash_{M}^{*} & (\sqcup abc \sqcup) & & (L_{\sqcup}) \\ & \vdash_{M} & (\sqcup \underline{a}bc \sqcup) & & (R) \\ & \vdash_{M} & (\sqcup \underline{\sqcup}bc \sqcup) & & (\sqcup) \end{array}$ 

What is the goal of the following Turing Machine?

$$> L_{\sqcup} \longrightarrow \underset{R_{\sqcup}}{\overset{a \neq \sqcup}{\longrightarrow}} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a$$

 $\begin{array}{cccc} (\sqcup abc \sqcup) & \vdash_{M}^{*} & (\sqcup abc \sqcup) & (L_{\sqcup}) \\ & \vdash_{M} & (\sqcup \underline{a}bc \sqcup) & (R) \\ & \vdash_{M} & (\sqcup \underline{\sqcup}bc \sqcup) & (\sqcup) \\ & \vdash_{M}^{*} & (\sqcup \sqcup bc \sqcup \underline{\sqcup}) & (R_{\sqcup}^{2}) \end{array}$ 

What is the goal of the following Turing Machine?

$$> L_{\sqcup} \longrightarrow R \xrightarrow{a \neq \sqcup} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a$$
$$\downarrow \sqcup$$
$$R_{\sqcup}$$

$$\begin{array}{cccc} (\sqcup abc \sqcup) & \vdash_{M}^{*} & (\amalg abc \sqcup) & (L_{\sqcup}) \\ & \vdash_{M} & (\sqcup \underline{a}bc \sqcup) & (R) \\ & \vdash_{M} & (\sqcup \bigsqcup bc \sqcup) & (\sqcup) \\ & \vdash_{M}^{*} & (\sqcup \sqcup bc \sqcup \underline{\sqcup}) & (R_{\sqcup}^{2}) \\ & \vdash_{M} & (\sqcup \sqcup bc \sqcup \underline{a}) & (a) \end{array}$$

What is the goal of the following Turing Machine?

$$> L_{\sqcup} \longrightarrow \underset{R_{\sqcup}}{\overset{a \neq \sqcup}{\longrightarrow}} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a$$

 $\begin{array}{cccc} (\sqcup abc \sqcup) & \vdash_{M}^{*} & (\amalg abc \sqcup) & (L_{\sqcup}) \\ & \vdash_{M} & (\sqcup \underline{a}bc \sqcup) & (R) \\ & \vdash_{M} & (\sqcup \underline{\sqcup}bc \sqcup) & (\sqcup) \\ & \vdash_{M}^{*} & (\sqcup \sqcup bc \sqcup \underline{\sqcup}) & (R_{\sqcup}^{2}) \\ & \vdash_{M} & (\sqcup \sqcup bc \sqcup \underline{a}) & (a) \\ & \vdash_{M}^{*} & (\sqcup \underline{\sqcup}bc \sqcup a) & (L_{\sqcup}^{2}) \end{array}$ 

What is the goal of the following Turing Machine?

$$> L_{\sqcup} \longrightarrow \underset{R_{\sqcup}}{\overset{a \neq \sqcup}{\longrightarrow}} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a$$

- $\begin{array}{cccc} (\sqcup abc \sqcup) & \vdash_{M}^{*} & (\sqcup abc \sqcup) & (L_{\sqcup}) \\ & \vdash_{M} & (\sqcup \underline{a}bc \sqcup) & (R) \\ & \vdash_{M} & (\sqcup \underline{\sqcup}bc \sqcup) & (\sqcup) \end{array}$ 
  - $\vdash^*_M (\sqcup \sqcup bc \sqcup \underline{\sqcup}) (R_{\sqcup}^2)$
  - $\vdash_M (\sqcup \sqcup bc \sqcup \underline{a}) \quad (a)$
  - $\vdash^*_M \ (\sqcup \underline{\sqcup} bc \sqcup a) \ (L^2_{\sqcup})$
  - $\vdash_M \quad (\sqcup \underline{a} bc \sqcup a) \qquad (a)$

What is the goal of the following Turing Machine?

$$> L_{\sqcup} \longrightarrow \underset{R_{\sqcup}}{\overset{a \neq \sqcup}{\longrightarrow}} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a$$

 $\begin{array}{ccc} (\sqcup abc \sqcup) & \vdash_M^* & (\sqcup abc \sqcup) & & (L_{\sqcup}) \\ & \vdash_M & (\sqcup \underline{a}bc \sqcup) & & (R) \end{array}$ 

$$\vdash_M (\sqcup \underline{\sqcup} bc \sqcup) \qquad (\sqcup)$$

$$\vdash_M^* \ (\sqcup \sqcup bc \sqcup \underline{\sqcup}) \ (R_{\sqcup}^2)$$

$$\vdash_M \quad (\sqcup \sqcup bc \sqcup \underline{a}) \quad (a)$$

$$\vdash_M^* (\sqcup \underline{\sqcup} bc \sqcup a) \qquad (L^2_{\sqcup})$$

$$\vdash_M (\sqcup \underline{a} bc \sqcup a) \qquad (a)$$

$$\vdash_M (\sqcup a\underline{b}c \sqcup a) \qquad (R)$$

What is the goal of the following Turing Machine?

$$> L_{\sqcup} \longrightarrow R \xrightarrow{a \neq \sqcup} \sqcup R_{\sqcup}^{2} a L_{\sqcup}^{2} a$$
$$\downarrow \sqcup R_{\sqcup}$$

$$\vdash_M (\sqcup \underline{\sqcup} bc \sqcup) \qquad (\sqcup)$$

$$\vdash^*_M \quad (\sqcup \sqcup bc \sqcup \underline{\sqcup}) \quad (R^2_{\sqcup})$$

$$\vdash_M \quad (\sqcup \sqcup bc \sqcup \underline{a}) \quad (a)$$

$$\vdash_M^* (\sqcup \underline{\sqcup} bc \sqcup a) \qquad (L^2_{\sqcup})$$

$$\vdash_M (\sqcup \underline{a} bc \sqcup a) \qquad (a)$$

$$\vdash_M (\sqcup a\underline{b}c \sqcup a) \qquad (R)$$

#### Solution:

transforms  $\sqcup w \sqcup$  to  $\sqcup w \sqcup w \sqcup$ 

- give an algorithmic description of how the Turing Machine works in finite and discrete steps
- ▶ what is allowed?

- give an algorithmic description of how the Turing Machine works in finite and discrete steps
- what is allowed?  $\rightarrow$  almost everything!!

- give an algorithmic description of how the Turing Machine works in finite and discrete steps
- what is allowed?  $\rightarrow$  almost everything!!

#### Example

M = "On input w:

- 1. scan the input from left to right to be sure that is member of  $a^{\ast}b^{\ast}c^{\ast}$  and  $\mathit{reject}$  if not
- 2. find the leftmost a in the tape and if such an a does not exist, then
  - ▶ scan the input for a *c* and if such a *c* exists then *reject* else *accept*
- 3. replace a by  $\hat{a}$
- 4. scan the input for the leftmost b and if such a b does not exist, then restore all b's (replace all  $\hat{b}$  by b) and goto 2
- 5. replace b by  $\hat{b}$
- 6. scan to the right for the first c and if such a c does not exist, then reject
- 7. replace c by  $\hat{c}$  and goto 4"

- give an algorithmic description of how the Turing Machine works in finite and discrete steps
- what is allowed?  $\rightarrow$  almost everything!!

#### Example

$$L = \{a^i b^j c^k : i \times j = k\}$$

M = "On input w:

- 1. scan the input from left to right to be sure that is member of  $a^{\ast}b^{\ast}c^{\ast}$  and  $\mathit{reject}$  if not
- 2. find the leftmost a in the tape and if such an a does not exist, then
  - ▶ scan the input for a *c* and if such a *c* exists then *reject* else *accept*
- 3. replace a by  $\hat{a}$
- 4. scan the input for the leftmost b and if such a b does not exist, then restore all b's (replace all  $\hat{b}$  by b) and goto 2
- 5. replace b by  $\hat{b}$
- 6. scan to the right for the first c and if such a c does not exist, then reject
- 7. replace c by  $\hat{c}$  and goto 4"

A language L is called **decidable** (or **Turing-decidable** or **recursive**) if there is a Turing Machine that decides it.

A language L is called **decidable** (or **Turing-decidable** or **recursive**) if there is a Turing Machine that decides it.

A language L is called **Turing-recognizable** (or **recursively enumerable**) if there is a Turing Machine that recognizes it.

#### Theorem

If a language L is decidable, then it is Turing-recognizable.

#### Theorem

If a language L is decidable, then it is Turing-recognizable.

Theorem

If a language L is decidable, then its complement  $\overline{L}$  is also.

### Proof.

#### Theorem

If a language L is decidable, then it is Turing-recognizable.

#### Theorem

If a language L is decidable, then its complement  $\overline{L}$  is also.

### Proof.

$$\delta'(q,a) = \left\{ \begin{array}{ll} n & \text{if } \delta(q,a) = y \\ y & \text{if } \delta(q,a) = n \\ \delta(q,a) & \text{otherwise} \end{array} \right.$$

$$(s, {\underline{\sqcup}} w) \vdash^*_M (h, {\underline{\sqcup}} y)$$

Then, y is the **output** of M on input w and is denoted by M(w).

$$(s, \underline{\sqcup} w) \vdash^*_M (h, \underline{\sqcup} y)$$

Then, y is the **output** of M on input w and is denoted by M(w).

Consider a function  $f: \Sigma^* \to \Sigma^*$ . We say that M computes the function f if M(w) = f(w) for all  $w \in \Sigma^*$ .

$$(s, \underline{\sqcup} w) \vdash^*_M (h, \underline{\sqcup} y)$$

Then, y is the **output** of M on input w and is denoted by M(w).

Consider a function  $f: \Sigma^* \to \Sigma^*$ . We say that M computes the function f if M(w) = f(w) for all  $w \in \Sigma^*$ .

A function f is called **decidable** (or **recursive**) if there is a Turing Machine that computes it.

$$(s, \underline{\sqcup} w) \vdash^*_M (h, \underline{\sqcup} y)$$

Then, y is the **output** of M on input w and is denoted by M(w).

Consider a function  $f: \Sigma^* \to \Sigma^*$ . We say that M computes the function f if M(w) = f(w) for all  $w \in \Sigma^*$ .

A function f is called **decidable** (or **recursive**) if there is a Turing Machine that computes it.

Example



The output with input  $\sqcup 100010111$  is ...
Consider a Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, \{h\})$  and a string  $w \in \Sigma^*$ . Suppose that M halts on input w and for some  $y \in \Sigma^*$  we have

$$(s, \underline{\sqcup} w) \vdash^*_M (h, \underline{\sqcup} y)$$

Then, y is the **output** of M on input w and is denoted by M(w).

Consider a function  $f: \Sigma^* \to \Sigma^*$ . We say that M computes the function f if M(w) = f(w) for all  $w \in \Sigma^*$ .

A function f is called **decidable** (or **recursive**) if there is a Turing Machine that computes it.

Example



The output with input  $\Box 100010111$  is ...  $\Box 100011000$ 

Computes the function succ(n) = n + 1 in binary

We have already seen an extension:

- write in the tape and move left or right at the same time
- ► modify the definition of the transition function initial: from (K \ H) × Γ to K × (Γ ∪ {←, →}) extended: from (K \ H) × Γ to K × Γ × {←, →}

We have already seen an extension:

- write in the tape and move left or right at the same time
- ► modify the definition of the transition function initial: from (K \ H) × Γ to K × (Γ ∪ {←, →}) extended: from (K \ H) × Γ to K × Γ × {←, →}
- ▶ if the extended Turing Machine halts on input w after t steps, then the initial Turing Machine halts on input w after at most 2t steps

A k-tape Turing Machine (M) is a sextuple  $(K, \Sigma, \Gamma, \delta, s, H)$ , where K,  $\Sigma$ ,  $\Gamma$ , s and H are as in the definition of the ordinary Turing Machine, and  $\delta$  is a transition function

 $\text{from} \quad (K \setminus H) \times \Gamma^k \quad \text{ to } \quad K \times (\Gamma \cup \{\leftarrow, \rightarrow\})^k$ 



A k-tape Turing Machine (M) is a sextuple  $(K, \Sigma, \Gamma, \delta, s, H)$ , where K,  $\Sigma$ ,  $\Gamma$ , s and H are as in the definition of the ordinary Turing Machine, and  $\delta$  is a transition function

from  $(K \setminus H) \times \Gamma^k$  to  $K \times (\Gamma \cup \{\leftarrow, \rightarrow\})^k$ (from  $(K \setminus H) \times \Gamma^k$  to  $K \times \Gamma^k \times \{\leftarrow, \rightarrow\}^k$ )



#### Theorem

Every k-tape, k > 1, Turing Machine  $M = (K, \Sigma, \Gamma, \delta, s, H)$  has an equivalent single tape Turing Machine  $M' = (K', \Sigma', \Gamma', \delta', s', H')$ .

If M halts on input  $w\in \Sigma^*$  after t steps, then M' halts on input w after O(t(|w|+t)) steps.

#### Sketch of the proof:

- M' simulates M in a single tape
- $\blacktriangleright$  # is used as delimiter to separate the contents of different tapes
- dotted symbols are used to indicate the actual position of the head of each tape
  - ▶ for each symbol  $\sigma \in \Gamma$ , add both  $\sigma$  and  $\overset{\bullet}{\sigma}$  in  $\Gamma'$
- use the same set of halting states



M' = "On input  $w = w_1 w_2 \dots w_n$ :

1. Format the tape to represent the  $\boldsymbol{k}$  tapes:

 $#w_1w_2\dots w_n\# \stackrel{\bullet}{\sqcup} \# \stackrel{\bullet}{\sqcup} \#\dots \#$ 

2. For each step that M performs, scan the tape from left to right to determine the symbols under the virtual heads. Then, do a second scan to update the tapes according to the transition function of M.

M' = "On input  $w = w_1 w_2 \dots w_n$ :

1. Format the tape to represent the  $\boldsymbol{k}$  tapes:

 $#w_1w_2\dots w_n\# \stackrel{\bullet}{\sqcup} \# \stackrel{\bullet}{\sqcup} \#\dots \#$ 

- 2. For each step that M performs, scan the tape from left to right to determine the symbols under the virtual heads. Then, do a second scan to update the tapes according to the transition function of M.
- If at any point there is a need to move a virtual head outside the area marked for the corresponding tape, then shift right the contents of all tapes succeeding."

M' = "On input  $w = w_1 w_2 \dots w_n$ :

1. Format the tape to represent the  $\boldsymbol{k}$  tapes:

 $#w_1w_2\dots w_n\# \stackrel{\bullet}{\sqcup} \# \stackrel{\bullet}{\sqcup} \#\dots \#$ 

- 2. For each step that M performs, scan the tape from left to right to determine the symbols under the virtual heads. Then, do a second scan to update the tapes according to the transition function of M.
- If at any point there is a need to move a virtual head outside the area marked for the corresponding tape, then shift right the contents of all tapes succeeding."

Number of steps for M':

**1**. O(|w|)

2. & 3. O(|w|+t) per step  $\Rightarrow O(t(|w|+t))$  in total

• size of the tape no more than O(|w|+t)

#### The multiple tape Turing Machine is **not** more powerful !!

The multiple tape Turing Machine is **not** more powerful !!

... but it is more easy to construct and to understand !

The multiple tape Turing Machine is **not** more powerful !!

 $\ldots$  but it is more easy to construct and to understand !

... and it can be used to simulate functions in an easier way (a function can use one or more not used tapes)





- $R^{1,2}$ : move the head of both tapes on the right
- $\sigma^2$  (as a state): write in the tape 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head of tape 2 reads the symbol  $\sigma$



- ► R<sup>1,2</sup>: move the head of both tapes on the right
- $\sigma^2$  (as a state): write in the tape 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head of tape 2 reads the symbol  $\sigma$

	tape 1	tape 2
initially	$\Box w$	
after (1)		



- ► R<sup>1,2</sup>: move the head of both tapes on the right
- $\sigma^2$  (as a state): write in the tape 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head of tape 2 reads the symbol  $\sigma$

	tape 1	tape 2
initially	$\Box w$	
after (1)	$\sqcup w \sqcup$	$\sqcup w \sqcup$
after (2)		



- ► R<sup>1,2</sup>: move the head of both tapes on the right
- $\sigma^2$  (as a state): write in the tape 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head of tape 2 reads the symbol  $\sigma$

	tape 1	tape 2
initially	$\Box w$	
after (1)	$\sqcup w \sqcup$	$\sqcup w \underline{\sqcup}$
after (2)	$\sqcup w \sqcup$	$\underline{\sqcup}w \sqcup$
at the end		



- ► R<sup>1,2</sup>: move the head of both tapes on the right
- $\sigma^2$  (as a state): write in the tape 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head of tape 2 reads the symbol  $\sigma$

	tape 1	tape 2
initially	$\Box w$	
after (1)	$\sqcup w \sqcup$	$\Box w \underline{\Box}$
after (2)	$\sqcup w \sqcup$	$\sqcup w \sqcup$
at the end	$\sqcup w \sqcup w \sqcup$	$\sqcup w \underline{\sqcup}$



extend notation:

- $R^{1,2}$ : move the head of both tapes on the right
- $\sigma^2$  (as a state): write in the tape 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head of tape 2 reads the symbol  $\sigma$

	tape 1	tape 2
initially	$\Box w$	
after (1)	$\sqcup w \sqcup$	$\sqcup w \underline{\sqcup}$
after (2)	$\sqcup w \sqcup$	$\sqcup w \sqcup$
at the end	$\sqcup w \sqcup w \underline{\sqcup}$	$\sqcup w \underline{\sqcup}$

transforms w to  $w \sqcup w$ 

### Definition (informal)

- ▶ at each step all heads can read/write/move
- ▶ we need a convention if two heads try writing in the same place

### Definition (informal)

- ▶ at each step all heads can read/write/move
- ▶ we need a convention if two heads try writing in the same place

#### Theorem

Every multiple head Turing Machine M has an equivalent single head Turing Machine M'.

The simulation by M' of M on an input w which leads to a halting state takes time quadratic to the size of the input |w| and the number of steps t that M performs.

### Definition (informal)

- ▶ at each step all heads can read/write/move
- ▶ we need a convention if two heads try writing in the same place

#### Theorem

Every multiple head Turing Machine M has an equivalent single head Turing Machine M'.

The simulation by M' of M on an input w which leads to a halting state takes time quadratic to the size of the input |w| and the number of steps t that M performs.

- scan the tape twice
  - 1 find the symbols at the head positions (which transition to follow?)
  - 2 write/move the heads according to the transition
- same arguments as before for the number of steps

### Definition (informal)

- ▶ at each step all heads can read/write/move
- ▶ we need a convention if two heads try writing in the same place

#### Theorem

Every multiple head Turing Machine M has an equivalent single head Turing Machine M'.

The simulation by M' of M on an input w which leads to a halting state takes time quadratic to the size of the input |w| and the number of steps t that M performs.

- scan the tape twice
  - 1 find the symbols at the head positions (which transition to follow?)
  - 2 write/move the heads according to the transition
- same arguments as before for the number of steps

### Definition (informal)

- ▶ at each step all heads can read/write/move
- ▶ we need a convention if two heads try writing in the same place

#### Theorem

Every multiple head Turing Machine M has an equivalent single head Turing Machine M'.

The simulation by M' of M on an input w which leads to a halting state takes time quadratic to the size of the input |w| and the number of steps t that M performs.

Proof (another one):

### Definition (informal)

- ▶ at each step all heads can read/write/move
- ▶ we need a convention if two heads try writing in the same place

#### Theorem

Every multiple head Turing Machine M has an equivalent single head Turing Machine M'.

The simulation by M' of M on an input w which leads to a halting state takes time quadratic to the size of the input |w| and the number of steps t that M performs.

Proof (another one):



# Multiple heads: example

Give a Machine Turing with two heads that transforms the input  $\underline{\Box}w$  to  $\underline{\Box}w \sqcup w$ .

- $\underline{\sigma}$ ,  $\overline{\sigma}$ ,  $\overline{\underline{\sigma}}$ : the position of the 1st, 2nd and both heads, respectively
- $R^{1,2}$ : move both heads on the right
- $\sigma^2$  (as a state): write in the position of head 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head 2 reads the symbol  $\sigma$

## Multiple heads: example

Give a Machine Turing with two heads that transforms the input  $\underline{\Box}w$  to  $\underline{\Box}w \sqcup w$ .

- $\underline{\sigma}$ ,  $\overline{\sigma}$ ,  $\overline{\underline{\sigma}}$ : the position of the 1st, 2nd and both heads, respectively
- $R^{1,2}$ : move both heads on the right
- $\sigma^2$  (as a state): write in the position of head 2 the symbol  $\sigma$
- $\sigma^2$  (as a label): if the head 2 reads the symbol  $\sigma$

$$> R^2_{\sqcup} R^{1,2} \xrightarrow{\sigma^1 \neq \sqcup} \sigma^2$$

$$\downarrow \sqcup^1$$

$$L^{1,2}_{\sqcup} L^2_{\sqcup}$$

## Unbounded tapes

What happens if the tape is bounded in one direction?

## Unbounded tapes

What happens if the tape is bounded in one direction?

#### Theorem

Every two-direction unbounded tape Turing Machine M has an equivalent single-direction unbounded tape Turing Machine.

### Definition (informal)

move the head left/right/up/down

### Definition (informal)

move the head left/right/up/down

Why?

### Definition (informal)

▶ move the head left/right/up/down

#### Why?

▶ for example, to represent more easily two-dimensional matrices

### Definition (informal)

▶ move the head left/right/up/down

#### Why?

▶ for example, to represent more easily two-dimensional matrices

### Theorem

Every two-dimensional tape Turing Machine M has an equivalent single-dimensional tape Turing Machine M'.

The simulation by M' of M on an input w which leads to a halting state takes time polynomial to the size of the input |w| and the number of steps t that M performs.

### Definition (informal)

▶ move the head left/right/up/down

#### Why?

▶ for example, to represent more easily two-dimensional matrices

### Theorem

Every two-dimensional tape Turing Machine M has an equivalent single-dimensional tape Turing Machine M'.

The simulation by M' of M on an input w which leads to a halting state takes time polynomial to the size of the input |w| and the number of steps t that M performs.

- use a multiple tape Turing Machine
- ▶ each tape corresponds to one line of the two-dimensional memory

## Discussion

 We can even combine the presented extensions and still not get a stronger model
## Discussion

- We can even combine the presented extensions and still not get a stronger model
- Observation: a computation in the prototype Turing Machine needs a number of steps which is bounded by a polynomial of the size of the input and of the number steps in any of the extended model